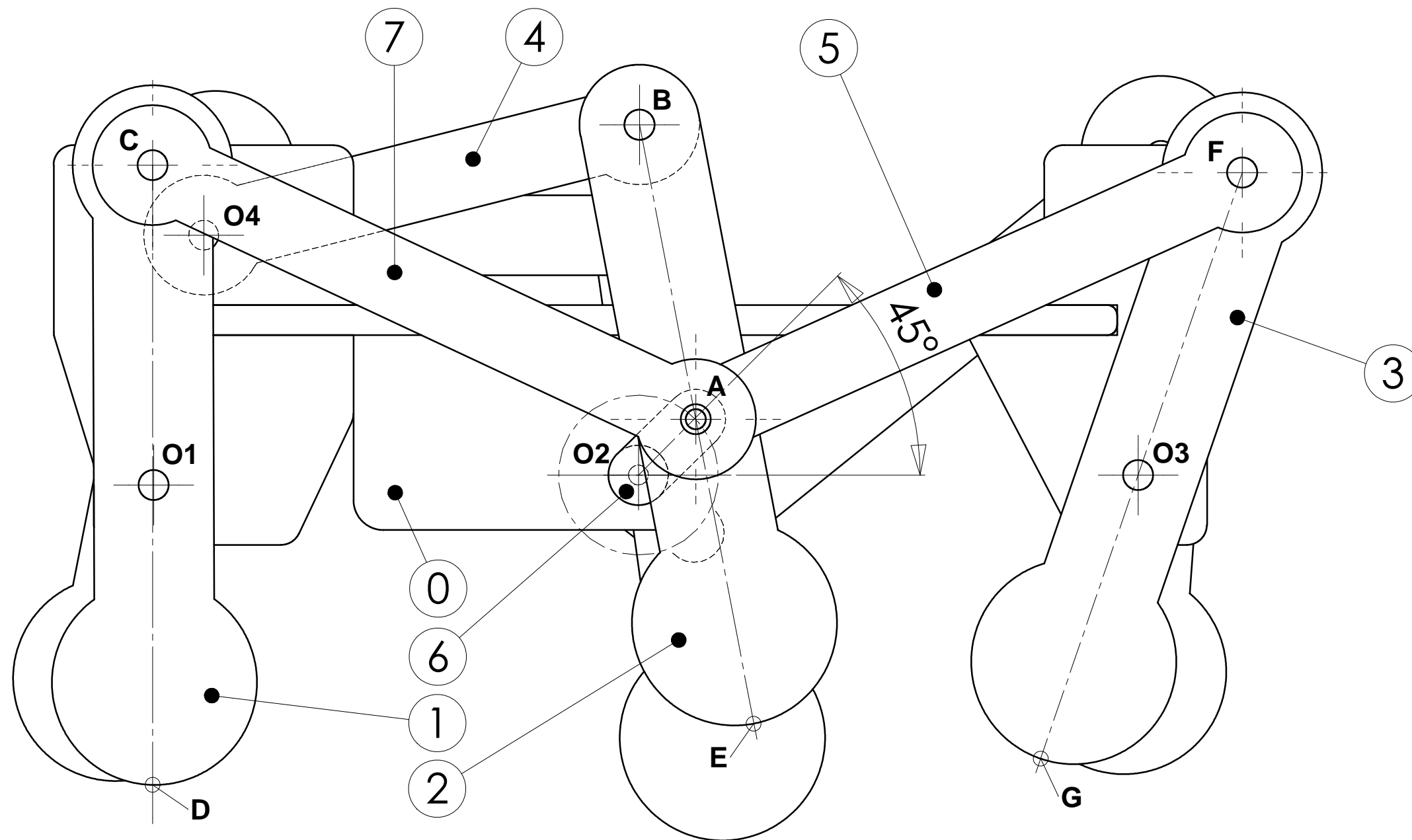
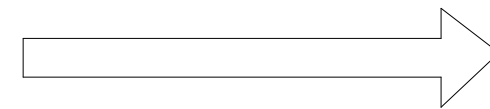


# Etude des trajectoires

$$O_2 A = 8\text{mm}$$

Sens de marche du robot



**Robot simulant la marche d'un insecte**